On the Potential of Multi-Objective Algorithm Configuration on Multi-Modal Multi-Objective Optimisation Problems

Oliver L. Preuß, Jeroen Rook, <u>Heike Trautmann</u> JOLEA talk, June 19, 2024 originally at: Evostar 2024 @ Aberystwyth: 03-05 April

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Talk Outline

!! This talk combines three different Multiobjective Perspectives – *MOO*³ **!!**

Multi-Objective Optimisation (Algorithms)

Multi-Objective Performance Measurement

Multi-Objective Automated Algorithm Configuration

... with special focus on Multimodality

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In a nutshell: We will present (automatically) optimized hyperparameter settings of evolutionary multiobjective optimizers



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- low-quality algorithmic components are a risk within larger AI pipelines
- use meta-algorithmic (Auto-ML)frameworks to (help) construct AI systems with robust components
- e.g. automated algorithm selection, automated algorithm configuration



The world is multi-objective ...

Multi-Objective Optimization (MOO)

- Multi-objective optimization problems (MOP) have multiple (conflicting) objectives
- · Solution is usually a set of trade-offs between objectives
- Find all solutions that are Pareto optimal



Many MOPs are multimodal ...

- Multiple global and local optima
- Different points in the decision space map to the same point in objective space



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 $\,\hookrightarrow\,$ Goal: <code>diverse</code> solution set in decision space and convergence towards Pareto front

How do we measure these criteria? ...

Diversity in Decision Space

Solow Polasky measure (SP)

[Solow & Polasky, '94]

- Pairwise distances of points
- Measures diversity of decision space
- Should be maximized



Convergence in Objective Space

Dominated hypervolume (HV)

[Zitzler et. al., '03]

- Area of non-dominated points and reference point *r*
- Accounts for convergence and spread in objective space
- \cdot To be maximized



Diversity: Solow-Polasky Measure

$$SP(P) = \sum_{1 \le i, j \le \mu} M_{ij}^{-1} \in [1, \mu]$$

- **P** Population of μ individuals
- M^{-1} Moore-Penrose generalised inverse matrix of M with $M_{i,j} = \exp(-d(P_i, P_j))$ d (Euclidean) distance between two individuals

Evolutionary Multi-Objective Optimisation Algorithms

Most Evolutionary Mult-Objective Algorithms (EMOAs) are not designed for diversity in decision space but rather for convergence and diversity in objective space



→ We will use automated algorithm configuration (AAC) to find EMOA hyperparameters that will (simultaneously) yield decision space diversity [Rook et al., '22]

- Rook et al., 2022 pointed to hyperparameter sensitivity
- Single-Objective Configurations for SP impacts convergence behavior (HV) and vice versa



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- Rook et al., 2022 pointed to hyperparameter sensitivity
- Single-Objective Configurations for SP impacts convergence behavior (HV) and vice versa
- Can we mitigate the trade-off between SP and HV?
- Use multi-objective AAC (MO-AAC) for HV and SP simultaneously



(Multi-Objective) Automated Algorithm Configuration

Automated Algorithm Configuration (AAC)

Find a configuration for an algorithm that optimises its overall performance

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$$\theta^* = \operatorname*{argmax}_{\theta \in \Theta} p(\mathsf{A}_{ heta}, \ \mathcal{I})$$

- $\boldsymbol{\Theta}$ Configuration space
- A Algorithm
- ${oldsymbol{\mathcal{I}}}$ Problem domain (usually represented by a set of instances (N))
- **p** Performance measure

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Challenges

- \cdot Large and mixed-type search spaces
- Expensive evaluations

Algorithm Configurators

- SMAC, ParamILS
- iRace, GGA, ...

Find a set of configurations for an algorithm that approaches the trade-off surface of the overall performances

Formulated as multi-objective optimisation problem:

$$\Theta^* = \{\theta \in \Theta \mid \nexists_{\theta' \in \Theta/\{\theta\}} p(A_{\theta'}, \mathcal{I}) \prec p(A_{\theta}, \mathcal{I})\}$$

Algorithm Configurators

- · MO-SMAC
- MO-ParamILS
- (ParEGO)

MO-SMAC

- Does not aggregate objectives
- Predicted Hypervolume improvement
- Returns set of configurations

SMAC: Key Steps

\cdot Initialization:

Generate initial configurations and evaluate their performance.

• Model Building:

Construct a probabilistic model of the performance across the configuration space.

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Model Building:

Construct a probabilistic model of the performance across the configuration space.

• Acquisition Function:

Use an acquisition function to select new configurations to evaluate, balancing exploration and exploitation.

\cdot Iteration:

Evaluate the selected configurations, update the model with the new data, and repeat the process.



Intensification: Process of selecting and re-evaluating promising configurations more frequently to ensure their performance is accurately assessed.

Empirical Performance Model: Gaussian Process Model (Bayesian Optimisation)

Modification 1: Intensification

- Incumbent is a population of configurations
- Racing continues until <u>closest</u>¹ configuration $\theta \in \Theta_{inc}$ <u>dominates</u> the challenger

Modification 2: Empirical performance model

• EPM based on Predicted Hypervolume Improvement

¹Based on the Euclidean distance between the aggregated performance on the overlapping instances 28

Modification 2: Empirical performance model



Experiments

Configurators: SMAC-SP, SMAC-HV, MO-SMAC

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- 7 EMOAs
 - NSGA-II, Omni-Optimizer, SMS-EMOA, MOEA/D, HIGA-MO, MOLE, MOGSA
- 33 test instances
 - ZDT (5), MMF (19), DTLZ (5) , BiObj-BBOB (3)
- 10-fold cross-validation (CV)
- 10 configuration runs per CV-fold
- 25 validation runs per instance



Overview Experiments / Research Questions



1. How competitive are EMOAs configured with (MO-)AAC?



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After MO configuration, we compare the two extreme non-dominated solutions to the SO configurations of SP and HV



- MO-SMAC finds better configurations for SP compared to SMAC-SP
- $\cdot\,$ SMAC and MO-SMAC find comparable configurations for HV

2a. How configurable are EMOAs?



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We assess the quality of the PF approximation in performance indicator space by the Hypervolume Indicator, i.e. HV*



(MO-)SMAC

HV*

 \hookrightarrow Omni-Optimizer outperforms all other EMOAs

2b. How configurable are EMOAs?



We assess the nondominated configurations generated by MO-SMAC separately regarding SP and HV in original objective space.



- \hookrightarrow Gradient-based EMOAs rank better for SP
- \hookrightarrow Omni-Optimizer outperforms all other EMOAs for SP
- $\,\hookrightarrow\,$ Classical EMOAs rank best for HV



- We will look at the non-dominated (MO-)AAC configurations per algorithm in detail
- We will investigate the trade-off behaviour per EMOA regarding SP and HV





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- We will investigate the trade-off behaviour per EMOA regarding SP and HV
- We will identify 'best trade-off solutions'

Algorithm	# configs	unique configs	non-dominated
MOLE	19	19	1
MOGSA	17	17	2
NSGA-II	27	27	4
HIGA-MO	17	17	3
MOEA/D	29	29	3
Omni-Optimizer	42	40	4
SMS-EMOA	23	23	3

- In general few non-dominated configurations
- · Omni-Optimizer has the most configurations
- · Omni-Optimizer and NSGA-II tie on non-dominated configurations
- \cdot (MO-) Configuration has a higher impact on SP

Trade-off behaviour per EMOA regarding SP and HV including best trade-off solutions





Joint view on EMOA trade-off behaviour: Overall best configurations



- 5 non-dominated overall configurations
- · Omni-Optimizer achieved the best overall performance

Summary & Conclusion



• We showed the huge potential of Multiobjective Automated Algorithm Configuration for EMOAs

Summary & Conclusion



- We showed the huge potential of Multiobjective Automated Algorithm Configuration for EMOAs
- Showed superiority of MO-AAC to SO-AAC
- Successfully analysed the trade-off between convergence in objective space and diversity in decision space
- · Showed configurability of EMOAs, Omni-Optimizer has overall best performance
- Proposed new default configurations for the considered setting

Future Work

- \cdot Widen the scope of the experimental study
- Extend decision (and objective) space
- Use additional benchmark sets, e.g., PeekABoo! [Schäpermeier et. al., '23]

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- Investigate MO-AAC as an optimization problem itself
- · Depending on the landscape other configurators like MO-ParamILS could work better

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- 'Vicious circle' of meta-configuration?
- Configurators can be configured as well

Multimodal Multi-objective Optimization: Bridging the Gap Between Problem Domains and Research Communities

– Workshop at PPSN 2024 –



Please join our workshop at PPSN 2024 ! ... organized by Oliver Schütze. Cinvestav-IPN. Mexico Lennart Schäpermeier, **TU Dresden** Heike Trautmann. Paderborn University

September, 14-18, Hagenberg, Austria (Workshop Sep. 15)