ESWC 2015 Tutorial <u>Publishing and Interlinking Linked Geospatial Data</u>

Part 1: Background in geospatial data modeling



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Outline

- Basic GIS concepts and terminology
- Representing geometries
- Representing topological information
- Geospatial data standards

Basic GIS Concepts and Terminology

Theme: the information corresponding to a particular domain that we want to model. A theme is a set of **geographic** features.

Example: the countries of Europe



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Basic GIS Concepts (cont'd)

Geographic feature or geographic object: a domain entity that can have various attributes that describe spatial and nonspatial characteristics.

Example: the country Greece with attributes

- Population
- Flag
- Capital
- Geographical area
- Coastline
- Bordering countries



Basic GIS Concepts (cont'd)

Geographic features can be **atomic** or **complex.**

Example: According to the Kallikratis administrative reform of 2010, Greece consists of:

- 13 **regions** (e.g., Crete)
- Each region consists of **regional units** (e.g., Heraklion)
- Each regional unit consists of **municipalities** (e.g., Dimos Chersonisou)



Basic GIS Concepts (cont'd)

The spatial characteristics of a feature can involve:

- **Geometric information** (location in the underlying geographic space, shape etc.)
 - Topological information (containment, adjacency etc.).

Municipalities of the regional unit of Heraklion:

1. Dimos Irakliou

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- 2. Dimos Archanon-Asterousion
- 3. Dimos Viannou
- 4. Dimos Gortynas
- 5. Dimos Maleviziou
- 6. Dimos Minoa Pediadas
- 7. Dimos Festou
- 8. Dimos Chersonisou



Geometric Information

Geometric information can be captured by using geometric primitives (**points**, **lines**, **polygons**, etc.) to approximate the spatial attributes of the real world feature that we want to model.



Geometries are associated with a **coordinate reference system** which describes the coordinate space in which the geometry is defined.

Encoding Geometries: Vector Representation

- In this encoding objects in space are represented using **points** as primitives as follows:
 - A **point** is represented by a tuple of coordinates.
 - A **line segment** is represented by a pair with its beginning and ending point.
 - More complex objects such as arbitrary lines, curves, surfaces etc. are built recursively by the basic primitives using constructs such as lists, sets etc.
 - This is the approach **used in all GIS and other popular systems today. It has also been standardized** by various international bodies.

Example



Encoding Geometries: Constraint Representation



Constraint Databases

- The constraint representation of spatial data was the focus of much work in **databases, logic programming and AI** after the paper by Kanellakis, Kuper and Revesz (PODS, 1991).
- The approach was very fruitful theoretically but was not adopted in practice.

Topological Information

- Topological information is **inherently qualitative** and it is expressed in terms of **topological relations** (e.g., containment, adjacency, overlap etc.).
 - Topological information can be **derived from geometric information** or it might be captured by **asserting explicitly the topological relations** between features.



Topological Relations

- The study of topological relations has produced a lot of interesting results by researchers in:
 - GIS
 - Spatial databases
 - Artificial Intelligence (qualitative reasoning and knowledge representation)

DE-9IM

- The dimensionally extended 9-intersection model (DE-9IM) of Clementini and Felice.
- It is based on the **point-set topology** of R².
- It deals with simple, closed and connected
 geometries (areas, lines, points).
 - It is an extension of earlier approaches: the **4intersection (4IM)** and **9-intersection (9IM)** models by Egenhofer and colleagues.

Topological Relations in DE-9IM

It captures topological relationships between two geometries *a* and *b* in R² by considering the dimensions of the intersections of the boundaries, interiors and exteriors of the two geometries:

$$\text{DE-9IM}(a,b) = \begin{bmatrix} \dim(I(a) \cap I(b)) & \dim(I(a) \cap B(b)) & \dim(I(a) \cap E(b)) \\ \dim(B(a) \cap I(b)) & \dim(B(a) \cap B(b)) & \dim(B(a) \cap E(b)) \\ \dim(E(a) \cap I(b)) & \dim(E(a) \cap B(b)) & \dim(E(a) \cap E(b)) \end{bmatrix}.$$

 The dimension can be 2, 1, 0 and -1 (dimension of the empty set).

Example



	I(C)	B (C)	E(C)
I(A)	-1	-1	2
B(A)	-1	-1	1
E(A)	2	1	2

Topological Relations in DE-9IM

- The following five **named relationships** between two different geometries can be distinguished: **disjoint, touches, crosses, within** and **overlaps**.
- The named relationships have a **reasonably intuitive meaning** for users. They are **jointly exclusive and pairwise disjoint** (JEPD).
- The model can also be defined using an appropriate **calculus of geometries** that uses these 5 binary relations and boundary operators.

Example: A disjoint C



	I(C)	B (C)	E(C)
I(A)	F	F	*
B (A)	F	F	*
E(A)	*	*	*

Notation: • T = { 0, 1, 2 }

- F = -1
- $* = don't care = \{ -1, 0, 1, 2 \}$



	I(C)	B (C)	E(C)
I(A)	Т	*	F
B (A)	*	*	F
E(A)	*	*	*

Notation equivalent to 3x3 matrix:

- String of 9 characters representing the above matrix in row major order.
- In this case: T*F**F***

DE-9IM Relation Definitions

Beziehung	Definition	Beispiele	
A disjoint B	FF* FF* ***	A B	
A touches B (d(A) > 0 v d(B) > 0)	$\begin{bmatrix} FT * \\ * * * \\ * * * \end{bmatrix} \lor \begin{bmatrix} F * * \\ T * * \\ * * * \end{bmatrix} \lor \begin{bmatrix} F * * \\ * T * \\ * * * \end{bmatrix}$		
A crosses B (d(A) < d(B))	T * T * * * * * * * * *		
A crosses B (d(A) = d(B) = 1)	0 * * * * * * * *	X	
A within B	T * F * * F * * *		
A overlaps B ($d(A) = d(B)$, $d(A) \neq 1$, $d(B) \neq 1$)	T * T * * * T * *		
A overlaps B ($d(A) = d(B) = 1$)	1 * T * * * T * *	1	

The Region Connection Calculus (RCC)

- The primitives of the calculus are spatial regions. These are non-empty, regular closed subsets of a topological space.
 - The calculus is based on a single binary predicate *C* that formalizes the "**connectedness**" relation.
 - **C(a,b)** is true when the closure of *a* is connected to the closure of *b* i.e., they have at least one point in common.
 - It is axiomatized using first order logic.

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 This is a set of eight JEPD binary relations that can be defined in terms of predicate C.



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- The RCC-5 subset has also been studied. The granularity here is coarser. The boundary of a region is not taken into consideration:
 - No distinction among DC and EC, called just DR.
 - No distinction among TPP and NTPP, called just PP.

RCC-8 and RCC-5 relations **can also be defined using point-set topology**, and there are very close connections to the models of Egenhofer and others.

More Qualitative Spatial Relations

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Orientation/Cardinal directions (left of, right of, north of, south of, northeast of etc.)



Distance (close to, far from etc.). This information can also be **quantitative**.

Coordinate Systems

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- **Coordinate:** one of *n* scalar values that determines the position of a point in an *n*-dimensional space.
- **Coordinate system:** a set of mathematical rules for specifying how coordinates are to be assigned to points.

Example: the Cartesian coordinate system



Coordinate Reference Systems

- Coordinate reference system: a coordinate system
 that is related to an object (e.g., the Earth, a planar
 projection of the Earth, a three dimensional
 mathematical space such as R³) through a datum
 which specifies its origin, scale, and orientation.
- The term **spatial reference system** is also used.

Geographic Coordinate Reference Systems

These are 3-dimensional coordinate systems that utilize **latitude** (ϕ) , **longitude** (λ) , and optionally **geodetic height** (i.e., elevation), to capture geographic locations on Earth.



The World Geodetic System

The **World Geodetic System (WGS)** is the most well-known geographic coordinate reference system and its latest revision is **WGS84.**

Applications: cartography, geodesy, navigation (GPS), etc.



Projected Coordinate Reference Systems

Projected coordinate reference systems: they transform the

3-dimensional approximation of the Earth into a 2-dimensional surface (distortions!)

Example: the Universal Transverse Mercator (UTM) system





Mercator projection

Transverse Mercator projection



Coordinate Reference Systems (cont'd)

- There are well-known ways to **translate** between coordinate reference systems.
- See the list of coordinate reference systems of the **European Petroleum Survey Group**: http://www.epsg-registry.org/

Geospatial Data Standards

The **Open Geospatial Consortium (OGC)** and the **International Organization for Standardization (ISO)** have developed many geospatial data standards that are in wide use today. In this tutorial we will cover:

- Well-Known Text
- Geography Markup Language
- OpenGIS Simple Features Access





WKT is an OGC and ISO standard for representing **geometries**, **coordinate reference systems**, and **transformations** between coordinate reference systems.

WKT is specified in **OpenGIS Simple Feature Access - Part 1: Common Architecture** standard which is the same as the **ISO 19125-1** standard. Download from

http://portal.opengeospatial.org/files/?artifact_id=25355 .

This standard concentrates on **simple features:** features with all spatial attributes described piecewise by a straight line or a planar interpolation between sets of points.

WKT Class Hierarchy







WKT representation:

Geography Markup Language (GML)

- **GML** is an **XML-based encoding standard** for the representation of geospatial data.
- GML provides XML schemas for defining a variety of concepts: geographic features, geometry, coordinate reference systems, topology, time and units of measurement.
- **GML profiles** are subsets of GML that target particular applications.
 - **Examples**: Point Profile, GML Simple Features Profile etc.

GML Simple Features: Class Hierarchy



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GML representation:

OpenGIS Simple Features Access

OGC has also specified a standard for the storage, retrieval, query and update of sets of simple features using relational DBMS and SQL.

This standard is **"OpenGIS Simple Feature Access - Part 2: SQL Option**" and it is the same as the **ISO 19125-2** standard. Download from http://portal.opengeospatial.org/files/?artifact_id=25354.

Related standard: ISO 13249 SQL/MM - Part 3.

OpenGIS Simple Features Access (cont'd)

The standard covers two implementations options: (i) using **only the SQL predefined data types** and (ii) using **SQL with geometry types**.

SQL with geometry types:

- We use the WKT geometry class hierarchy presented earlier to define **new geometric data types for SQL**
- We define new **SQL functions on those types**.

SQL with Geometry Types -Functions

Functions that **request or check properties** of a geometry:

- ST Dimension (A:Geometry): Integer
- ST_GeometryType(A:Geometry):Character Varying
- ST_AsText(A:Geometry): Character Large Object
- ST_AsBinary(A:Geometry): Binary Large Object
- ST_SRID(A:Geometry): Integer
- ST_IsEmpty(A:Geometry): Boolean
- ST_IsSimple(A:Geometry): Boolean

SQL with Geometry Types – Functions (cont'd)

Functions that test **topological relations** between two geometries using the **DE-9IM**:

- ST_Equals (A:Geometry, B:Geometry):Boolean
- ST_Disjoint(A:Geometry, B:Geometry):Boolean
- ST_Intersects (A:Geometry, B:Geometry):Boolean
- ST_Touches (A:Geometry, B:Geometry):Boolean
- ST Crosses (A:Geometry, B:Geometry):Boolean
- ST_Within (A:Geometry, B:Geometry):Boolean
- ST_Contains (A:Geometry, B:Geometry):Boolean
- ST_Overlaps (A:Geometry, B:Geometry):Boolean
- ST_Relate(A:Geometry, B:Geometry, Matrix: Char(9)):Boolean

DE-9IM Relation Definitions

Beziehung	Definition	Beispiele	
A disjoint B	F F * F F * * * *	A B	 A equidefined b TFFFTF
A touches B (d(A) > 0 v d(B) > 0)	$\begin{bmatrix} \mathbf{F} \mathbf{T}^* \\ * * * \\ * * * \end{bmatrix} \lor \begin{bmatrix} \mathbf{F}^* * \\ \mathbf{T}^* * \\ * * * \end{bmatrix} \lor \begin{bmatrix} \mathbf{F}^* * \\ * \mathbf{T}^* \\ * * * \end{bmatrix}$		• A inte
A crosses B (d(A) < d(B))	T * T * * * * * * * * *		negation
A crosses B (d(A) = d(B) = 1)	0 * * * * * * * *	X	• A con to B with
A within B	T * F * * F * * *	•	
A overlaps B (d(A) = d(B), $d(A) \neq 1,$ $d(B) \neq 1)$	T * T * * * T * *		
A overlaps B ($d(A) = d(B) = 1$)	1 * T * * * T * *	8	

• A equals B can also be defined by the pattern TFFFTFFT.

• A intersects B is the negation of A disjoint B

A contains B is equivalent
 to B within A

SQL with Geometry Types – Functions (cont'd)

- Functions for **constructing new geometries** out of existing ones:
 - ST_Boundary (A:Geometry) :Geometry
 - ST_Envelope(A:Geometry):Geometry
 - ST_Intersection (A:Geometry, B:Geometry):Geometry
 - ST_Union (A:Geometry, B:Geometry):Geometry
 - ST_Difference(A:Geometry, B:Geometry):Geometry
 - ST_SymDifference(A:Geometry, B:Geometry):Geometry
 - ST_Buffer(A:Geometry, distance:Double):Geometry

Geospatial Relational DBMS

The OpenGIS Simple Features Access Standard is today been used in all **relational DBMS with a geospatial extension.**

- The **abstract data type mechanism** of the DBMS allows the representation of all kinds of geospatial data types supported by the standard.
- The query language (SQL) offers the **functions** of the standard for querying data of these types.



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Readings

- The book *Geographic Information Systems and Science* is a nice introduction to GIS. See: <u>http://eu.wiley.com/WileyCDA/WileyTitle/productCd-EHEP001475.html</u>
- The following papers present the DE-9IM model:

Eliseo Clementini, Paolino Di Felice and Peter van Oosterom.

A Small Set of Formal Topological Relationships Suitable for End-User Interaction. SSD 1993: 277-295

http://link.springer.com/chapter/10.1007%2F3-540-56869-7_16

E. Clementini and P. Felice. A Comparison of Methods for Representing Topological Relationships. Information Sciences 80 (1994), pp. 1-34. http://www.sciencedirect.com/science/article/pii/106901159400033X The paper

The paper below surveys a lot of interesting results on the RCC calculus: J. Renz, B. Nebel, Qualitative Spatial Reasoning using Constraint

Calculi, in: M. Aiello, I. Pratt-Hartmann and J. van Benthem (eds.),

Handbook of Spatial Logics, pp. 161–215, 2007, Springer. http://users.cecs.anu.edu.au/~jrenz/papers/renz-nebel-los.pdf

• The two OGC standards mentioned in the slides.